Development of a Photogrammetric Processing Workflow for UAV-based Multispectral Imagery

Student Research Colloquium 2017 Forest Information Technology (M.Sc.) 4th Semester Max Kampen



Universität für Bodenkultur Wien Department für Raum, Landschaft und Infrastruktur





General Information

3rd Semester's Research project was part of a feasibility study carried out by the Institute of Surveying, Remote Sensing and Land Information (IVFL) at the University of Natural Resources and Life Sciences, Vienna



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Content

- Introduction
- Methodology
- Results
- Conclusions



Supervisor

Dipl.-Ing. Markus Immitzer MSc.

Peter-Jordan-Straße 82

1190 Wien

Email: markus.immitzer(at)boku.ac.at

Tel: +43 1 47654-85732





Methodology

Introduction

- Flexibility is of crucial importance when monitoring forest disturbances like bark beetle (*Ips typographus* or *Pityogenes chalcographus*) infestation in order to develop mitigation strategies and initiate timely countermeasures
- Satellite remote sensing is too inflexible and terrestrial monitoring too time-consuming and cost-intensive



Introduction Methodology

Introduction

 Research group aims to develop a data acquisition and processing method for multitemporal UAV-based multispectral imagery, which could enable flexible low-cost monitoring of tree species distribution and forest disturbances





Objectives & Research Questions

- Development of a photogrammetric processing workflow
- Is it possible to sufficiently distinguish different tree species by their spectral signatures?
- Is it possible to detect differences in health statuses between individual trees?



Literature Research



Results

Literature Research

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	A	В	С	D	E	F	G	Н	I
1	Author&Title	Subject 👻	Goals	Species 👻	Material	Methods 👻	Data Processing & Image analysis	Output	Notes 👻
6	Fassnacht, F. E., Latifi, H., Ghosh, A., Joshi, P. K., & Koch, B. (2014) Assessing the potential of hyperspectral imagery to map bark beetle-induced tree mortality	tree detection and classification detection of bark beetle infestation	 - assess mapping accuracies of bark beetle-induced tree mortality in 3 scenarios with differing target classes - identify crucial spectral regions to map bark beetle- induced tree mortality 	Mainly Norway spruce - Picea abies Bark beetle - Ips typographus	- HyMap hyperspectral data (airplane) - Airborne CIR imagery	- corrections in ATCOR4 and ORTHO software - HyMap and CIR images co- registered - CIR-based training samples for tree mortality classes as reference data -> Green Mortality Stage, Early Mortality Stage, Late Mortality Stage, Healthy Coniferous, Healthy Broadleaved, Bare Soil, Sparsely vegetated	 - samples for tree mortality classes selected with manually drawn polygons in CIR images - Genetic Algorithm (GA) for hyperdimensional classification - parameter tuning for classification - SVM classifier used 	 reported accuracies for delineation of early mortality stages were rather low, so that a combination of genetic algorithm and supervised classification was not sufficient for feature separation substantial over- classification of the Green Mortality Stage class, which in turn can be explained by the double confusion with the Healthy Coniferous and the Early Mortality Stage class main problem associated with accurate mapping of late mortality stages is rather differentiating among dead trees, bare soil and sparsely vegetated soil (possible to improve with height information) Genetic algorithm selected green peak (approx. 560 nm), the chlorophyll absorption feature (680 nm) and the red-edge (690 nm) as bands contributing most to high classification accuracies 	 - NIR plateau (1076 nm, 1069 nm) and 1532 nm have been found to be good estimators of water content and vegetation damage
7	Lausch, A., Heurich, M., Gordalla, D., Dobner, H. J., Gwillym-Margianto, S., & Salbach, C. (2013) Forecasting potential bark beetle outbreaks based on spruce forest vitality using hyperspectral remote- sensing techniques at different scales.	detection of bark beetle infestation	prediction of outbreak potential of bark beetle infestation based on detection of different vitality stages of spruce that provide prediction indicators	Norway spruce - Picea abies Bark heetle - Ips typographus	- HyMap hyperspectral data (airplane)	 classification of 5 different spruce vitality conditions/infestation stages from different years using long time vector data and hyperspectral data (resolutions 4m & 7m) ID3 decision tree classification method 	- pixel-based 4m & 7m - ATCOR4 & ORTHO - ENVI 4.7	 Important spectral information for derivation vitality status of spruce are 450-890 nm Hyperspectral data with 4 m grain contain more relevant information to estimate differences in vitality of spruce than 7 m Imited use of spectral information 1400-1800 nm (part of SWIR) insufficient differentiation accuracy between early stage and healthy class 	450-890 nm: wavebands related to prominent chlorophyll absorption features 1400-1800 nm: reflects the water content of needles
8	Yuan, Y., & Hu, X. (2016) Random forest and objected- based classification for forest pest extraction from uav aerial imagery	detection of forest pests	presenting random forest and object-based classification for forest pest detection in UAV aerial imagery		- UAV imagery	- segmentation of image into "superpixels" - The zero parameter version of the SLIC algorithm is used for choosing an adaptive compactness factor - random forest (algorithm) model and validated classification	 image segmentation is performed by the simple lineariterative clustering (SUC) algorithm proposed by R. Achanta in2012(R. Achanta et al., 2012) 	approach can effectively detect all of the visually salient pest areas from the UAV imagery - high potential of UAV aerial imagery for forest pest infestation monitoring - strong positive economic advantage over the traditionally applied ground based forest pest detection - limited data amount, algorithm needs to be tested for different conditions	"random forest is much faster in training and testing than traditional classifiers (such as an SVM)" said to be robust to outlying observations

Fig. 1: Screenshot of information table created during literature research

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Methodology

Results

UAV - Setup



Fig. 2: UAV-Setup with all four jointly mounted camera systems. (Arrows indicate position of the respective camera)





Camera Systems

Table 1: Specifications of utilized cameras

Camera system	Imagery	Wavelengths	Resolution [pixels]
GoPro Hero 4 Black	3-band-RGB	400 – 700 nm	4000 x 3000
Tetracam ADC Snap	3-band-multispectral	520 – 920 nm	1280 x 1024
AIRPHEN	6-band-multispectral	450 – 850 nm	1280 x 960
FLIR VUE Pro Thermal	1-band-thermal	7.5 – 13.5 µm	640 x 512



Fig. 4: AIRPHEN



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Fig. 5: CIR-image recorded by Tetracam ADC Snap



Fig. 6: Image recorded by AIRPHEN 450nm band



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Fig. 5: CIR-image recorded by Tetracam ADC Snap

07.05.2017



Fig. 6: Image recorded by AIRPHEN 450nm band





Methodology

Results

Conclusion

Investigation Area



Fig. 7: Location map of the investigation area showing the position within Austria (red mark) in the upper left corner and the approximate position and extent of the study site (yellow mark) close to Heidenreichstein.





Data Acquisition

- 10 flight survey days (May September 2016)
- Adjusted flight altitude and speed to cover investigation area with one battery charge
- Inhomogeneous data due to different weather conditions and luminosity changes during flights
- Tetracam recorded 300 images/flight
- AIRPHEN recorded around 650 images/flight for all 6 spectral bands (450, 530, 560, 675, 730 and 850 nm)



Introduction Methodology

Processing

- Creation of camera calibration files with Agisoft Lens
 0.4.2 to account for each camera's inner orientation
- Photogrammetric processing (point clouds, 3D-models, DEMs and orthomosaics) performed in *Agisoft PhotoScan professional 1.2.6*
- Creation of tree crown mask for object-based analysis in ArcGIS 10.3
- Layer stacking and analysis of crown pixel values (DN) performed with *raster* package (Hijmans & van Etten, 2014) in *RStudio*



General Workflow

- 1. Image Matching \rightarrow Sparse Point Cloud
- 2. Optimizing Image Orientation \rightarrow Marking GCPs
- 3. Dense Point Cloud Computing & Editing
- 4. Creation of 3D-Model & Texture
- 5. Creation of Digital Surface Model (DSM)
- 6. Compute Orthomosaic

!!!! Processing parameters were adjusted according to initial processing trials and evaluation **!!!!**



1. Image Matching

 Table 2: Parameter settings for the image alignment and sparse cloud generation in Agisoft PhotoScan

Parameters	Settings	
Accuracy	Medium	High
Pair selection	Generic	Generic
Key point limit	40,000	40,000
Tie point limit	2,000	4,000
Adaptive camera model fitting	Enabled	Enabled



Methodology

Results

Conclusion

1. Image Matching



Fig. 8: Sparse Cloud derived from AIRPHEN 450nm band imagery through image matching / alignment process



Methodology

Results

Conclusion

2. Optimizing Image Orientation



Fig. 9: Image from AIRPHEN 450nm band with a marked ground control point (GCP)

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Methodology

Results

Conclusion

Difficulties Marking GCPs



Fig. 10: Images of AIRPHEN imagery depicting difficult conditions for marking of GCPs





3. Dense Point Cloud Computing & Editing

- Dense cloud quality and depth filtering proved to be most influential parameters for tree representation in later orthomosaics
- Quality: Ultrahigh
- Depth filtering: Mild



Methodology

Results

Conclusion

3. Dense Point Cloud Computing & Editing



Fig. 11: Sparse Cloud derived from AIRPHEN 450nm band imagery through image matching / alignment process



Methodology

Results

Conclusion

3. Dense Point Cloud Computing & Editing



Fig. 12: Comparison of tree features in differently processed orthomosaics from AIRPHEN 450nm band imagery (red frame indicating optimal quality and depth filtering settings for dense point clouds)





Methodology

Results

Conclusion

3. Dense Point Cloud Computing & Editing



Fig. 13: Comparison of tree features in differently processed orthomosaics from AIRPHEN 450nm band imagery (red frame indicating optimal quality and depth filtering settings for dense point clouds)





Methodology

Results

Conclusion

3. Dense Point Cloud Computing & Editing



Fig. 14: Comparison of tree features in differently processed orthomosaics from AIRPHEN 450nm band imagery (red frame indicating optimal quality and depth filtering settings for dense point clouds)





Introduction Methodology

3. Dense Point Cloud Computing & Editing

 Manual removal of outliers above canopy height and under ground level (necessary for correct DSM)



Fig. 15: Screenshots depicting manual removal of outliers in a dense cloud derived from AIRPHEN imagery



Methodology

Results

4. Creation of 3D-Model & Texture

- Just intermediate steps
- Highlighted settings were recommended for aerial imagery

Table 3:	Settings	for 3D-Model	creation
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Parameters	Settings
Surface type	Height field
Blending mode	Mosaic (default)
Face count	Medium (default)
Interpolation	Enabled

 Table 4: Settings for Texture creation

Parameters	Settings
Mapping mode	Orthophoto
Blending mode	Mosaic (default)
Texture	4096 (default)
size/count	
Color correction	Disabled
Hole filling	Enabled





Methodology

Results

Conclusion

5. Creation of Digital Surface Model (DSM)

DSM was derived from the dense point cloud



Fig. 16: Derived Digital Surface Model (DSM) in different displaying variants

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Introduction Methodology

6. Compute Orthomosaic

- Computation of orthomosaics based on DSM delivered best results
- Produced 6 separate AIRPHEN orthomosaics for different spectral bands
- Performed mutlilayer stack in raster package for RStudio



Fig. 17: Concept of layer stack for AIRPHEN orthomosaics



Results

Conclusion

AIRPHEN Multilayer Stack







Results

Conclusion

AIRPHEN Multilayer Stack







Methodology

Results

Conclusion

AIRPHEN Multilayer Stack



Fig. 19: Excerpt of Multilayer Stack with two stressed spruces (yellow marks)

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Methodology

Results

Conclusion

Extraction of Pixel Values (DN)



Fig. 20: Concept of pixel value extraction using tree crown mask and raster package in RStudio

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Methodology

Results

Initial Analysis – Tree Species



Wavelength [nm]

Fig. 21: Spectral profiles of occurring tree species, derived through plotting the mean digital number values (data from 10/07/2016) for each species against the respective wavelength of AIRPHEN spectral bands.



Methodology

Initial Analysis – Health Status



Wavelength [nm]

Fig. 22: Spectral profiles of a healthy and a stressed spruce, derived through plotting the mean digital number values (data from 10/07/2016) for both trees against the respective wavelength of AIRPHEN spectral bands.



Conclusion

- Results emphasize suitability of the data for future automatic tree species determination and classification
- Data is adequate for the detection of forest disturbances
- Early detection of bark beetle infestation is uncertain
- Gained valuable information for the improvement of future data acquisition



Outlook & Further Research tasks

- Improve data comparability by calculating reflectance values from DN
- Automatic Tree Segmentation via Canopy Height Models
- Exclusion of shaded crown parts via masking algorithms (Fassnacht et al., 2014)
- Implement normalization procedures and plant health indices (e.g. NDVI family)
- Optimization of flight planning



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Image Sources

- Slide 9:
 - Fig. 3: Tetracam ADC Snap <u>http://www.termocam.it/images/stories/virtuemart/product/adc-snap.jpg</u> [16.01.2017]
 - Fig. 4: AIRPHEN

http://www.hiphen-plant.com/docs/airphen_solid_coupe.png [16.01.2017]



Thanks for your attention!



Universität für Bodenkultur Wien Department für Raum, Landschaft und Infrastruktur

Student

Max Kampen BSc.

Am Platz 4 / 6

1130 Vienna, AUSTRIA

Email: max.kampen@hnee.de

max.kampen@students.boku.ac.at

Tel: +43 (0)677 623 631 89

+49 (0)151 207 265 83

Supervisor

Dipl.-Ing. Markus Immitzer MSc. Peter-Jordan-Straße 82 1190 Vienna, AUSTRIA Email: markus.immitzer@boku.ac.at Tel: +43 1 47654-85732